# MCMC: An Intermediate Example

STAT 946: Advanced Bayesian Computing

## The Noncentral-t Distribution

**Definition:** Let  $z \sim \mathcal{N}(\mu, \sigma^2)$  II  $x \sim \chi^2_{(\nu)}$ . Then  $y = \frac{z}{\sqrt{x/\nu}} + \eta$ 

has a Noncentral Student-*t* (NCT) distribution, denoted  $y \sim t_{(\nu)}(\mu, \sigma, \eta)$ .

## The Noncentral-t Distribution

**Definition:** Let  $z \sim \mathcal{N}(\mu, \sigma^2)$  II  $x \sim \chi^2_{(\nu)}$ . Then

$$y = rac{z}{\sqrt{x/
u}} + \eta \sim t_{(
u)}(\mu, \sigma, \eta).$$

**Modeling:** Allows very general specification of mean, variance, skewness and kurtosis.



## Parameter Inference

Model:

$$y_i \stackrel{\text{iid}}{\sim} t_{(\nu)}(\mu, \sigma, \eta) \qquad \Longleftrightarrow \qquad y_i = \frac{z_i}{\sqrt{x_i/\nu}} + \eta, \qquad \begin{array}{c} z_i \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \sigma^2) \\ x_i \stackrel{\text{iid}}{\sim} \chi^2_{(\nu)} \end{array}$$

- Observed Data:  $y_{obs} = y = (y_1, \ldots, y_n)$ .
- Missing Data:  $y_{\text{miss}} = x = (x_1, \dots, x_n)$ .
- **Complete Data:**  $y_{comp} = (y, x)$ , with

$$\begin{aligned} x_i &\stackrel{\text{iid}}{\sim} \chi^2_{(\nu)} \\ y_i \mid x_i \stackrel{\text{ind}}{\sim} \mathcal{N}(\eta + \gamma/x_i^{1/2}, \tau^2/x_i), \end{aligned}$$

where  $\gamma = \mu \nu^{1/2}$  and  $\tau = \sigma \nu^{1/2}$ .

## Parameter Inference

$$\begin{aligned} x_i &\stackrel{\text{iid}}{\sim} \chi^2_{(\nu)} & \gamma = \mu \nu^{1/2}, \\ y_i &| x_i &\stackrel{\text{ind}}{\sim} \mathcal{N}(\eta + \gamma/x_i^{1/2}, \tau^2/x_i), & \tau = \sigma \nu^{1/2}. \end{aligned}$$

• Inference: Let 
$$\theta = (\eta, \gamma, \tau^2, \nu)$$
.

EM Algorithm: This would require taking expectations of x, x<sup>1/2</sup>, and log x with respect to

$$p(x \mid y, \theta) \propto \exp\left\{-\frac{1}{2}\frac{(y-\eta-\gamma x^{-1/2})^2}{\tau^2/x} + \frac{1}{2}\log x + \left(\frac{\nu-2}{2}\right)\log x - \frac{x}{2}\right\}$$
$$\propto \exp\left\{Ax + Bx^{1/2} + C\log x\right\},$$

a nonstandard distribution (don't even know its normalizing constant).

## Parameter Inference

Model: 
$$y_i \stackrel{\text{iid}}{\sim} t_{(\nu)}(\mu, \sigma, \eta)$$
  
Observed Data:  $y_{\text{obs}} = y = (y_1, \dots, y_n).$   
Complete Data:  $y_{\text{comp}} = (y, x)$ , with  
 $x_i \stackrel{\text{iid}}{\sim} \chi^2_{(\nu)},$   
 $y_i \mid x_i \stackrel{\text{ind}}{\sim} \mathcal{N}(\eta + \gamma/x_i^{1/2}, \tau^2/x_i).$   
Inference: Let  $\theta = (\eta, \gamma, \tau^2, \nu).$   
EM Algorithm: Requires expectations wrt  
 $p(x \mid y, \theta) \propto \exp{\{Ax + Bx^{1/2} + C \log x\}}.$   
Bayesian Data Augmentation:

- 1. Implement an MCMC algorithm on the augmented posterior distribution
- If (x<sup>(1)</sup>, θ<sup>(1)</sup>),..., (x<sup>(M)</sup>, θ<sup>(Y)</sup>), ∞ p(y, x | θ) × π(θ).
   If (x<sup>(1)</sup>, θ<sup>(1)</sup>),..., (x<sup>(M)</sup>), θ<sup>(Y)</sup>) is an MCMC sample from p(x, θ | y), then the stationary distribution of θ<sup>(1)</sup>,..., θ<sup>(M)</sup> is p(θ | y) = ∫ p(x, θ | y)dx.
   (Works for exactly the same reason that the histogram of each random variable

(Works for exactly the same reason that the histogram of each random variable in any MCMC converges to its marginal distribution.)

Complete Data Likelihood: Don't cancel out anything involving θ or x:

$$\ell(\boldsymbol{\theta} \mid \boldsymbol{x}, \boldsymbol{y}) = \log p(\boldsymbol{y}, \boldsymbol{x} \mid \boldsymbol{\theta})$$
  
=  $-\frac{1}{2} \sum_{i=1}^{n} \left[ \frac{(y_i - \eta - \gamma x_i^{-1/2})^2}{\tau^2 / x_i} - (\nu - 1) \log x_i + x_i \right]$   
 $- n \left[ \frac{\tau^2 + \nu}{2} + \log \Gamma(\nu/2) \right].$ 

- MCMC Algorithm: A block Metropolis-within-Gibbs sampler with the following conditional updates:
  - Update for  $(\eta, \gamma, \tau)$ : Canceling everything that doesn't depend on  $\beta = (\eta, \gamma)$  and  $\tau$ , conditional likelihood  $\ell(\beta, \tau \mid \nu, \mathbf{x}, \mathbf{y})$  is that of a regression-like model

$$y_i \stackrel{\text{ind}}{\sim} \mathcal{N}(\boldsymbol{u}_i'\boldsymbol{eta}, \tau^2/x_i), \qquad \boldsymbol{u}_i = (1, 1/x_i^{1/2}).$$

Complete Data Likelihood:

$$\ell(\boldsymbol{\theta} \mid \boldsymbol{x}, \boldsymbol{y}) = -\frac{1}{2} \sum_{i=1}^{n} \left[ \frac{(y_i - \eta - \gamma x_i^{-1/2})^2}{\tau^2 / x_i} - (\nu - 1) \log x_i + x_i \right] - n \left[ \frac{\tau^2 + \nu}{2} + \log \Gamma\left(\frac{\nu}{2}\right) \right]$$

MCMC Algorithm: A block Metropolis-within-Gibbs sampler with:

• Update for  $(\eta, \gamma, \tau)$ : Canceling everything that doesn't depend on  $\beta = (\eta, \gamma)$  and  $\tau$ , conditional likelihood  $\ell(\beta, \tau \mid \nu, \mathbf{x}, \mathbf{y})$  is that of a regression-like model

$$y_i \stackrel{\text{ind}}{\sim} \mathcal{N}(\boldsymbol{u}_i' \boldsymbol{\beta}, \tau^2 / x_i), \qquad \boldsymbol{u}_i = (1, 1/x_i^{1/2})$$

 Conjugate Prior: Multivariate Normal Inverse-Gamma (mNIX) distribution

 $(\boldsymbol{eta}, au^2) \sim \mathsf{mNIX}(\boldsymbol{\lambda}, \boldsymbol{\Sigma}, \alpha, \gamma) \qquad \Longleftrightarrow \qquad \begin{aligned} & au^2 \sim \mathsf{Inv-Gamma}(\alpha, \gamma) \ & \boldsymbol{eta} \mid au^2 \sim \mathcal{N}(\boldsymbol{\lambda}, au^2 \cdot \boldsymbol{\Sigma}). \end{aligned}$ 

 $\implies$  Exact Gibbs update for  $p(\beta, \tau^2 \mid \nu, \mathbf{x}, \mathbf{y})$ .

ł

### Complete Data Likelihood:

$$\mathcal{L}(\boldsymbol{\theta} \mid \boldsymbol{x}, \boldsymbol{y}) = -\frac{1}{2} \sum_{i=1}^{n} \left[ \frac{(y_i - \eta - \gamma x_i^{-1/2})^2}{\tau^2 / x_i} - (\nu - 1) \log x_i + x_i \right] - n \left[ \frac{\tau^2 + \nu}{2} + \log \Gamma\left(\frac{\nu}{2}\right) \right]$$

MCMC Algorithm: A block Metropolis-within-Gibbs sampler with:

Update for v: Conditional likelihood is

ℓ(ν | η, γ, τ, x, y) = -n log Γ(<sup>1</sup>/<sub>2</sub>ν) - <sup>1</sup>/<sub>2</sub>ν × (n log(2) - ∑<sup>n</sup><sub>i=1</sub> log x<sub>i</sub>).
 Proposal Distribution: Conditional likelihood only depends on x<sub>i</sub> <sup>iid</sup> χ<sup>2</sup><sub>(ν)</sub> which is an Exponential Family ⇒ ℓ(ν | η, γ, τ, x, y) is convex. Could do Newton-Raphson to obtain a mode-quadrature normal approximation, but easier to use a random walk proposal.

▶ **Prior Distribution:** Use log  $\nu \sim \mathcal{N}(0, 2^2)$ . Basically uninformative, since  $\Pr(.005 < \nu < 170) \approx 99\%$  (recall that  $t_{(\nu=1)} \sim$  Cauchy and  $t_{(\nu\geq 30)} \approx \mathcal{N}(0, 1)$ ). Think of this prior as regularizing inference (i.e., prevents  $\nu$  from floating off to 0 or  $\infty$ ).

Complete Data Likelihood:

$$\ell(\boldsymbol{\theta} \mid \boldsymbol{x}, \boldsymbol{y}) = -\frac{1}{2} \sum_{i=1}^{n} \left[ \frac{(y_i - \eta - \gamma x_i^{-1/2})^2}{\tau^2 / x_i} - (\nu - 1) \log x_i + x_i \right] - n \left[ \frac{\tau^2 + \nu}{2} + \log \Gamma\left(\frac{\nu}{2}\right) \right]$$

MCMC Algorithm: A block Metropolis-within-Gibbs sampler with:

Update for x: Conditional posterior is

$$p(\mathbf{x} \mid \mathbf{y}, \boldsymbol{\theta}) \propto \prod_{i=1}^{n} \exp \left\{ A_i x_i + B_i x_i^{1/2} + C \log x_i \right\}.$$

- Proposal Distribution:
  - Note that the x<sub>i</sub> are conditionally independent given everything else ⇒ exact Gibbs sampler produces IID samples.
  - Could do MWG, but this requires n tuning parameters (one for each x<sub>i</sub>).
  - Note that mode of  $Ax + Bx^{1/2} + C \log x$  has an analytic solution
    - $\implies$  tuning-free MIID-within-Gibbs mode-quadrature proprosal.

# Proposal Distribution for $p(x \mid y, \theta)$



# MCMC Code Checking

- Much more difficult than checking that  $\hat{\theta} = \arg \max_{\theta} \ell(\theta \mid \mathbf{y})$ , since
  - MCMC is a random algorithm
  - Don't know much about p(θ | y) that's why we're doing MCMC in the first place!
- Recommendation: check code meticulously at every step. Whenever I skip a step, 99% of time there will be an error and then I don't know if it's in the last step or the one(s) I skipped. So I end up checking every step anyway, except now it takes longer.

# Code Checking Strategies

Compare every *simplified* conditional likelihood ℓ(θ<sub>i</sub> | θ<sub>-i</sub>, y) to the *unsimplified* likelihood log p(y | θ).
 Difference between the two for any value of θ<sub>i</sub> should be equal to a constant (possibly)

depending on  $\mathbf{y}$  and  $\boldsymbol{\theta}_{-j}$ ).

Compare every simplified posterior p(θ<sub>j</sub> | θ<sub>-j</sub>, y) to the unsimplified posterior L(θ | y) × π(θ).

Same as for loglikelihoods, but now checking Jacobians, i.e., if prior is  $\pi(\theta)$  but sampling is done on  $\psi = g(\theta)$ , then  $\pi(\psi) = \pi(g^{-1}(\psi)) \left| \frac{\partial}{\partial \psi} g^{-1}(\psi) \right|$ .

- Compare sampling from p(θ<sub>j</sub> | θ<sub>-j</sub>, y) to analytic conditional.
   To get analytic conditional, recall that p(θ<sub>j</sub> | θ<sub>-j</sub>, y) ∝ L(θ | y) × π(θ), to normalize evaluate 1-d integral numerically.
- 4. Compare sampling from  $p(\theta | y)$  for given MCMC to sample from same posterior with a different MCMC.

Both samplers should give same results.

Notation:  $\boldsymbol{\theta} = (\mu, \sigma, \eta, \nu), \ \boldsymbol{\varphi} = (\eta, \gamma = \mu \nu^{1/2}, \tau^2 = \sigma^2 \nu, \nu) = (\boldsymbol{\beta}, \tau^2, \nu).$ 

1. Simplified vs unsimplified likelihoods:  $\ell(\eta, \gamma, \tau^2 \mid \nu, \mathbf{x}, \mathbf{y}), \ \ell(\nu \mid \eta, \gamma, \tau^2, \mathbf{x}, \mathbf{y}), \ \log p(\mathbf{x} \mid \varphi, \mathbf{y}) \ \text{can each be checked against}$ 

$$p(\mathbf{y}, \mathbf{x} \mid \varphi) = \underbrace{p(\mathbf{y} \mid \mathbf{x}, \eta, \gamma, \tau^2)}_{\stackrel{\text{ind}}{\sim} \mathcal{N}(\eta + \gamma \mathbf{x}^{-1/2}, \tau^2 \mathbf{x}^{-1})} \times \underbrace{p(\mathbf{x} \mid \nu)}_{\stackrel{\text{iid}}{\sim} \chi^2_{(\nu)}}$$

Notation:  $\boldsymbol{\theta} = (\mu, \sigma, \eta, \nu), \ \boldsymbol{\varphi} = (\eta, \gamma = \mu \nu^{1/2}, \tau^2 = \sigma^2 \nu, \nu) = (\boldsymbol{\beta}, \tau^2, \nu).$ 

### 2. Conditional updates:

- ▶  $p(\nu \mid ...)$  and  $p(x_i \mid ...)$  compare to analytic 1D posterior  $\propto p(\mathbf{y}, \mathbf{x} \mid \varphi) \pi(\varphi)$ .
- ▶ Prior:  $\log(\nu) \sim \mathcal{N}(\mu_{\nu}, \sigma_{\nu}^2)$   $\beta, \tau^2 \mid \nu \sim \text{mNIX}(\alpha, \gamma, \lambda, \Sigma)$ As  $\sigma_{\nu}, \Sigma \to \infty$  and  $\alpha, \gamma \to 0$  this becomes  $\pi(\varphi) \propto 1/\tau^2$
- To check  $p(\beta, \tau^2 \mid \nu, \mathbf{x}, \mathbf{y}) = \text{mNIX}(\hat{\alpha}, \hat{\gamma}, \hat{\lambda}, \hat{\Sigma})$ , note that for any  $\mathbf{a} \in \mathbb{R}^2$ ,

$$au^2 \mid 
u, oldsymbol{x}, oldsymbol{y} \sim \mathsf{Inv} ext{-}\mathsf{Gamma}(\hat{lpha}, \hat{,} \gamma), \qquad rac{oldsymbol{a}'oldsymbol{eta} - oldsymbol{a}'\hat{oldsymbol{\lambda}}}{\sqrt{\hat{\gamma}/\hat{lpha}} \cdot oldsymbol{a}'\hat{\Sigma}oldsymbol{a}}} \mid 
u, oldsymbol{x}, oldsymbol{y} \sim t_{(2\hat{lpha})}$$

Note that the second result integrates out  $\tau^2$ .

Notation:  $\boldsymbol{\theta} = (\mu, \sigma, \eta, \nu), \ \boldsymbol{\varphi} = (\eta, \gamma = \mu \nu^{1/2}, \tau^2 = \sigma^2 \nu, \nu) = (\boldsymbol{\beta}, \tau^2, \nu).$ 

### 3. Unconditional Updates:

- Compare to an MIID sampler with mode-quadrature normal proposals for  $p(\theta \mid \mathbf{y}) = p(\mathbf{y} \mid \theta)\pi(\theta)$ .
- *p*(*y* | θ) available through R's built-in function dt with ncp parameter.
- $\pi(\theta)$  obtained from  $\pi(\varphi)$  through Jacobian. That is, if  $f_{\varphi}(\varphi)$  is PDF of prior on  $\varphi$ , then PDF of prior on  $\theta$  is  $f_{\theta}(\theta) = f_{\varphi}(\varphi) \times |d\varphi/d\theta|$ , where

$$\frac{\mathrm{d}\varphi}{\mathrm{d}\theta} = \begin{bmatrix} 0 & \nu^{1/2} & 0 & 0\\ 0 & 0 & 2\sigma\nu & 0\\ 1 & 0 & 0 & 0\\ 0 & \frac{1}{2}\mu\nu^{-1/2} & \sigma^2 & 1 \end{bmatrix} \implies \left| \frac{\mathrm{d}\varphi}{\mathrm{d}\theta} \right| = 2\sigma\nu^{3/2}.$$

Notation:  $\boldsymbol{\theta} = (\mu, \sigma, \eta, \nu), \ \boldsymbol{\varphi} = (\eta, \gamma = \mu \nu^{1/2}, \tau^2 = \sigma^2 \nu, \nu) = (\boldsymbol{\beta}, \tau^2, \nu).$ 

#### 4. Compare to different MCMC on same posterior:

- Since this is a 4-parameter problem, probably easiest to compare to MIID sampling with normal mode-quadrature proposals.
- For more complicated problems, perhaps easier to use a general-purpose MCMC, which will be slow but easy to program.
- **Stan:** The state-of-the-art in general-purpose MCMC.
  - Stan is a programming language very similar to R to which you input an arbitrary  $\log p(\theta \mid y)$ .
  - Implements and compiles in C++ a very effective MCMC algorithm called Hybrid Monte Carlo (HMC), but usually referred to as Hamiltonian Monte Carlo.