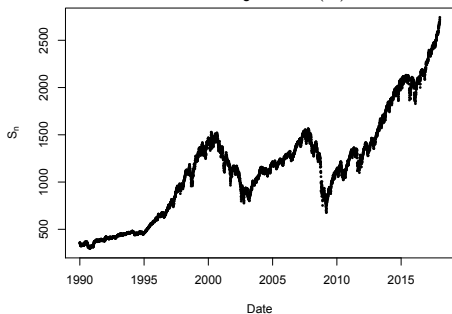


# Stochastic Differential Equations

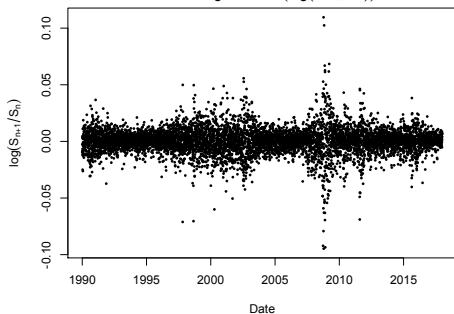
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# Motivation

GSPC: Original Scale ( $S_n$ )



GSPC: Log>Returns ( $\log(S_{n+1}/S_n)$ )



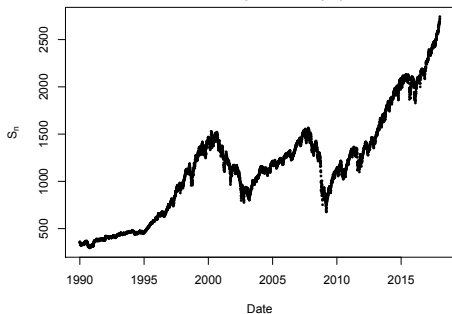
- **Data:** Daily GSPC (S&P500) closing prices between 1990-2018:

$$\mathbf{S} = (S_1, \dots, S_N), \quad N = 7060.$$

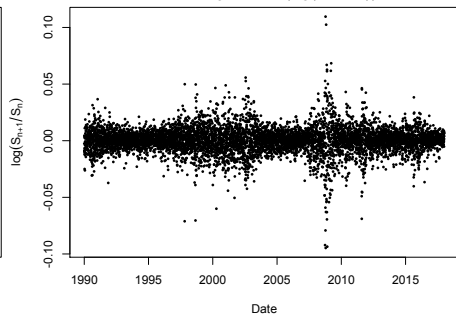
- **Goal:** Fit a model and use it to make forecasts

# Motivation

GSPC: Original Scale ( $S_n$ )



GSPC: Log>Returns ( $\log(S_{n+1}/S_n)$ )



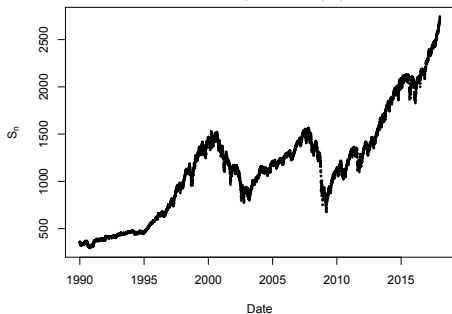
- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$
- ▶ **Model:** From 1900 till about 1989, this was a **stochastic differential equation** (SDE) called **Geometric Brownian motion**:

$$dS_t = \alpha S_t dt + \sigma S_t dB_t,$$

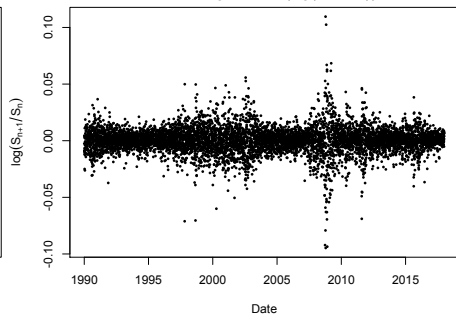
where  $S_t$  is the price at time  $t \in \mathbb{R}$  and  $B_t$  is Brownian motion.

# Motivation

GSPC: Original Scale ( $S_n$ )



GSPC: Log>Returns ( $\log(S_{n+1}/S_n)$ )



► **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$

► **Model:** From 1900 till about 1989, this was a **stochastic differential equation** (SDE) called **Geometric Brownian motion**:

$$dS_t = \alpha S_t dt + \sigma S_t dB_t, \quad \text{What do these symbols mean???$$

where  $S_t$  is the price at time  $t \in \mathbb{R}$  and  $B_t$  is Brownian motion.

# Stochastic Differential Equations

► **Definition:** Let  $X_t$  be a continuous-time stochastic process for which the following hold:

1. Almost every sample path is continuous.
2.  $X_t$  has the homogeneous Markov property:

$$\begin{aligned} p(X_{t+s} | \{X_u = x_u : u \leq t\}) &= p(X_{t+s} | X_t = x_t) \\ &= p(X_s | X_0 = x_t). \end{aligned}$$

Then (up to mathematical singularity)  $X_t$  is a **diffusion process** which can be described with a **stochastic differential equation**

$$dX_t = \mu(X_t) dt + \sigma(X_t) dB_t,$$

where:

- $\mu(x)$  and  $\sigma(x)$  (or  $\sigma^2(x)$ ) are the drift and diffusion functions
- $B_t$  is **Brownian motion**.

# Brownian Motion

- ▶ **Diffusion Process:**  $X_t$  continuous & Markov
- ▶ **SDE:**  $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$
- ▶ **Brownian Motion:**  $B_t$  is the *only* process with the following properties:
  1. Almost every sample path is *continuous*.
  2. *Independent increments:* If  $t_0 < t_1 < \dots < t_N$ , then

$$B_{t_1} - B_{t_0} \quad \text{II} \quad B_{t_2} - B_{t_1} \quad \text{II} \quad \dots \quad \text{II} \quad B_{t_N} - B_{t_{N-1}}$$

3.  $B_t$  is a *Gaussian process* with  $B_{s+t} - B_s \sim \mathcal{N}(0, t)$ . (Typically assumed that  $B_0 = 0$ )
- ▶ **Mean and Variance:** Turns out that properties 1-3 completely determine the distribution of  $B_t$ , such that

$$E[B_t] = 0, \quad \text{cov}(B_t, B_s) = \min(t, s).$$

# Brownian Motion

- ▶ **Definition:**  $B_t$  is a continuous Gaussian process with  $E[B_t] = 0$  and  $\text{cov}(B_t, B_s) = \min(t, s)$
- ▶ **Simulation:** To simulate  $B_t$  at times  $0 < t_1 < \dots < t_N$ , i.e., to generate  $\mathbf{B} = (B_{t_1}, \dots, B_{t_N})$ 
  - ▶ *Method 1:* Let  $\mathbf{\Sigma} = \text{var}(\mathbf{B}) \iff \Sigma_{ij} = \min(t_i, t_j)$ , then set  $\mathbf{B} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma})$ .  
However, this requires  $\mathbf{\Sigma}^{1/2}$ , which is  $\mathcal{O}(N^3)$ .

# Brownian Motion

- ▶ **Definition:**  $B_t$  is a continuous Gaussian process with  $E[B_t] = 0$  and  $\text{cov}(B_t, B_s) = \min(t, s)$
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  - ▶ *Method 1:* Let  $\Sigma = \text{var}(\mathbf{B}) \iff \Sigma_{ij} = \min(t_i, t_j)$ , then set  $\mathbf{B} \sim \mathcal{N}(\mathbf{0}, \Sigma)$ .  
However, this requires  $\Sigma^{1/2}$ , which is  $\mathcal{O}(N^3)$ .
  - ▶ *Method 2:* Use **independent increment** property

$$B_{t_{i+1}} - B_{t_i} \quad \text{II} \quad B_{t_{j+1}} - B_{t_j}, \quad i \neq j.$$

Therefore, letting  $t_0 = 0$ ,  $\Delta B_i = B_{t_{i+1}} - B_{t_i}$ , and  $\Delta t_i = t_{i+1} - t_i$ :

1. Draw  $\Delta B_i \stackrel{\text{ind}}{\sim} \mathcal{N}(0, \Delta t_i)$  for  $i = 0, \dots, N-1$
2. Let  $B_{t_n} = \sum_{i=0}^{n-1} \Delta B_i$ .

This method of simulation is only  $\mathcal{O}(N)$ .



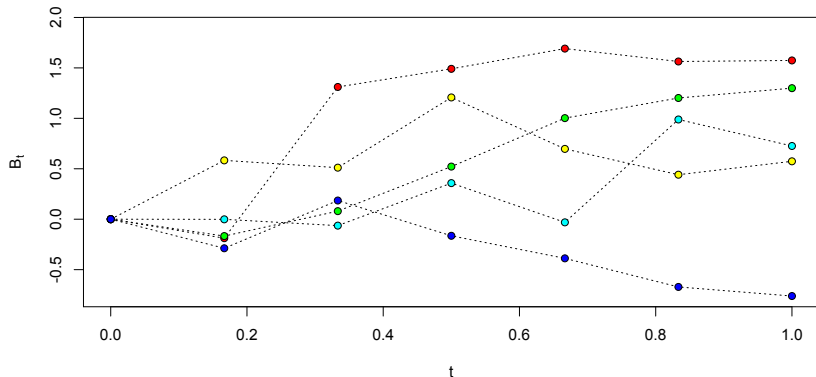
# Brownian Motion

► **Simulation:** To simulate  $B_t$  on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Draw  $\Delta B_i \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \Delta t)$

2. Let  $B_{n\Delta t} = \sum_{i=0}^{n-1} \Delta B_i$

►  $T = 1, N = 6$ :



# Brownian Motion

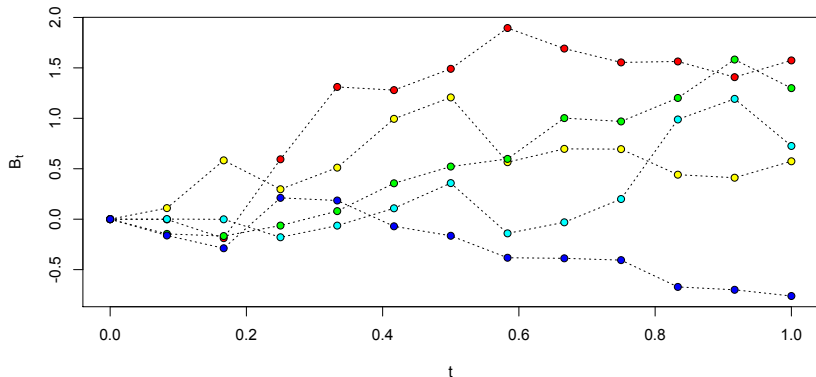
► **Simulation:** To simulate  $B_t$  on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Draw  $\Delta B_i \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \Delta t)$

2. Let  $B_{n\Delta t} = \sum_{i=0}^{n-1} \Delta B_i$

►  $T = 1, N = 12$ : **Infill** using **Markov property** with

$$B_t \mid B_{t-s}, B_{t+u} \sim \mathcal{N}(\sigma^2\{B_{t-s}/s + B_{t+u}/u\}, \sigma^2), \quad \sigma^2 = 1/(1/s + 1/u)$$



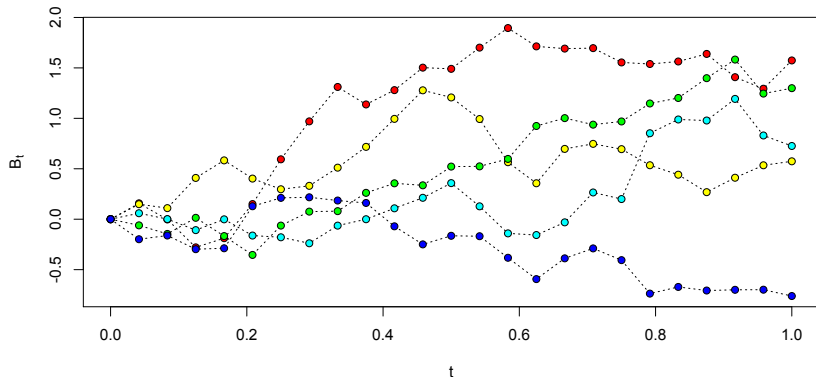
# Brownian Motion

► **Simulation:** To simulate  $B_t$  on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Draw  $\Delta B_i \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \Delta t)$

2. Let  $B_{n\Delta t} = \sum_{i=0}^{n-1} \Delta B_i$

►  $T = 1, N = 24$ :



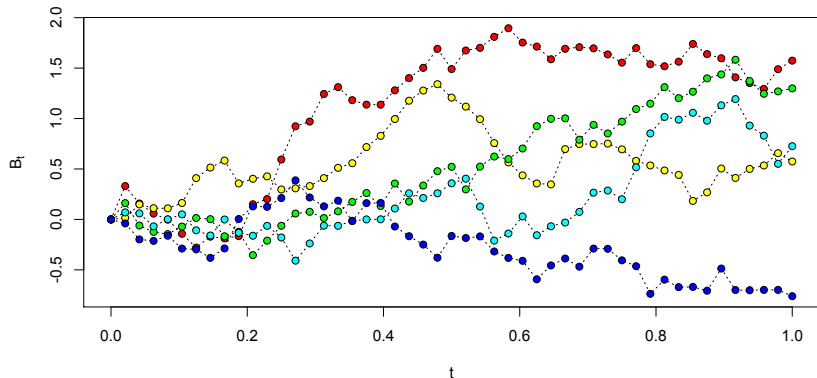
# Brownian Motion

► **Simulation:** To simulate  $B_t$  on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Draw  $\Delta B_i \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \Delta t)$

2. Let  $B_{n\Delta t} = \sum_{i=0}^{n-1} \Delta B_i$

►  $T = 1, N = 48$ : (As  $N \rightarrow \infty$  get a **continuous** process but **nowhere differentiable**)



# Stochastic Differential Equations (Continued)

- ▶ **Diffusion Process:**  $X_t$  continuous & Markov
- ▶ **SDE:**  $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$
- ▶ **Example 1:**  $dX_t = dB_t$ . (so  $\mu(x) = 0$  and  $\sigma(x) = 1$ .) Solution is

$$X_t = X_0 + \int_0^t dX_s = X_0 + \int_0^t dB_s = X_0 + B_t,$$

i.e., Brownian motion.

# Stochastic Differential Equations (Continued)

► **Diffusion Process:**  $X_t$  continuous & Markov

► **SDE:**  $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$

► **Example 1:**  $dX_t = dB_t$ . (so  $\mu(x) = 0$  and  $\sigma(x) = 1$ .) Solution is

$$X_t = X_0 + \int_0^t dX_s = X_0 + \int_0^t dB_s = X_0 + B_t,$$

i.e., Brownian motion.

► **Example 2:**  $dX_t = \mu dt + \sigma dB_t$ . Solution is

$$X_t = X_0 + \int_0^t \mu ds + \int_0^t \sigma dB_s = X_0 + \mu t + \sigma B_t,$$

i.e., Brownian motion with drift.

# Stochastic Differential Equations

- ▶ **Diffusion Process:**  $X_t$  continuous & Markov
- ▶ **SDE:**  $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$
- ▶ **Example 3:** General case.
  - ▶ Unfortunately,  $p(X_t | X_0)$  is typically intractable (solution to a PDE).
  - ▶ *Small-Time Approximation:* use the [Euler Discretization](#).

# Euler Discretization

► **Ordinary Differential Equation:**

$$\frac{dX_t}{dt} = G(X_t), \quad X_0 = x_0.$$

Typically these are intractable.

► **Euler Discretization:** Replace infinitesimal  $dt$  by time interval  $\Delta t$ :

$$\frac{dX_t}{dt} = G(X_t) \implies \frac{\Delta X_t}{\Delta t} \approx G(X_t) \implies \Delta X_t \approx G(X_t)\Delta t,$$

where  $\Delta X_t = X_{t+\Delta t} - X_t$ .

► **Approximate Solution:** To **approximate** ODE on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Let  $\tilde{X}_0 = x_0$ .
2. Let  $\tilde{X}_{n+1} = \tilde{X}_n + G(\tilde{X}_n)\Delta t$ .



# Euler Discretization

- ▶ **Ordinary Differential Equation:**  $\frac{dX_t}{dt} = G(X_t)$ .
- ▶ **Euler Discretization:**  $\frac{dX_t}{dt} = G(X_t) \implies \Delta X_t \approx G(X_t)\Delta t$ .
- ▶ **Approximate Solution:** To **approximate** ODE on  $[0, T]$  at intervals of  $\Delta t = T/N$ :
  1. Let  $\tilde{X}_0 = x_0$ .
  2. Let  $\tilde{X}_{n+1} = \tilde{X}_n + G(\tilde{X}_n)\Delta t$ .
- ▶ **Convergence:** If  $\tilde{X}_t^{(N)}$  is a linear interpolation of the approximated path skeleton with  $\Delta t = T/N$ , then

$$\lim_{N \rightarrow \infty} \left\{ \sup_{0 \leq t \leq T} (\tilde{X}_t^{(N)} - X_t)^2 \right\} = 0.$$

# Euler Discretization

► **Stochastic Differential Equation:**

$$dX_t = \mu(X_t) dt + \sigma(X_t) dB_t, \quad X_0 = x_0.$$

Typically these are intractable.

► **Euler Discretization:** Replace infinitesimal  $dt$  by time interval  $\Delta t$ :

$$dX_t = \mu(X_t) dt + \sigma(X_t) dB_t \quad \implies \quad \Delta X_t = \mu(X_t)\Delta t + \sigma(X_t)\Delta B_t,$$

where  $\Delta X_t = X_{t+\Delta t} - X_t$ , and  $\Delta B_t = B_{t+\Delta t} - B_t \sim \mathcal{N}(0, \Delta t)$ .

► **Approximate Solution:** To **approximate** SDE on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

1. Let  $\tilde{X}_0 = x_0$ .

2. Let  $\tilde{X}_{n+1} = \tilde{X}_n + \mu(\tilde{X}_n)\Delta t + \sigma(\tilde{X}_n)\Delta B_n, \quad \Delta B_0, \dots, \Delta B_{N-1} \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \Delta t)$ .

# Euler Discretization

► **Stochastic Differential Equation:**  $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$ .

► **Euler Discretization:**

$$dX_t = \mu(X_t) dt + \sigma(X_t) dB_t \implies \Delta X_t = \mu(X_t)\Delta t + \sigma(X_t)\Delta B_t.$$

► **Approximate Solution:** To **approximate** SDE on  $[0, T]$  at intervals of  $\Delta t = T/N$ :

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► **Convergence:** If  $\tilde{X}_t^{(N)}$  is a linear interpolation of the approximated path skeleton with  $\Delta t = T/N$ , then

$$\lim_{N \rightarrow \infty} \left\{ \sup_{0 \leq t \leq T} E [(\tilde{X}_t^{(N)} - X_t)^2] \right\} = 0.$$

# Example: Geometric Brownian Motion

► **Model:**  $dS_t = \alpha S_t \Delta t + \sigma S_t dB_t.$

("S" stands for stock: this is the model used for GSPC)

► **Analytic Solution:**  $S_t = S_0 \cdot \exp \left\{ \left( \alpha - \frac{1}{2} \sigma^2 \right) t + \sigma B_t \right\}.$

(In fact,  $X_t = \log(S_t)$  is Brownian Motion + drift:  $dX_t = \left( \alpha + \frac{1}{2} \sigma^2 \right) dt + \sigma dB_t.$ )

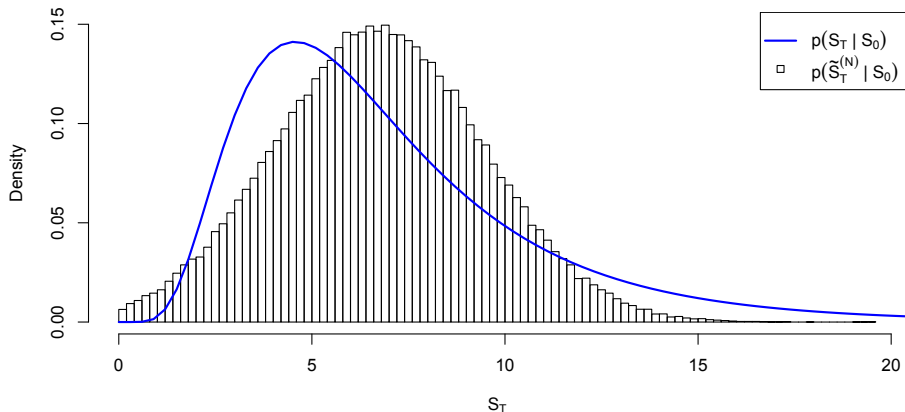
► **Euler Approximation:**  $S_t \approx S_0 + \alpha S_0 t + \sigma S_0 B_t.$

► **Simulation Study:** Compare true  $p(S_T | S_0)$  to approximate  $p(\tilde{S}_T^{(N)} | S_0)$  for

$$\alpha = .1, \quad \sigma = .3, \quad S_0 = 5.1, \quad T = 3.2.$$

# Example: Geometric Brownian Motion

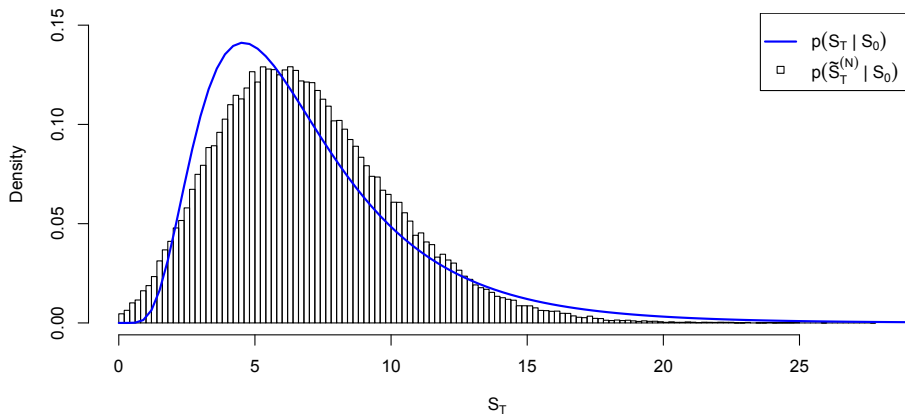
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$
- ▶ **Simulation:**  $\alpha = .1, \sigma = .3, S_0 = 5.1, T = 3.2$  -  $N = 1$  ( $\Delta t = T/N$ )



(Note that  $S_T > 0$  but  $\tilde{S}_T^{(N)} \in \mathbb{R}$ )

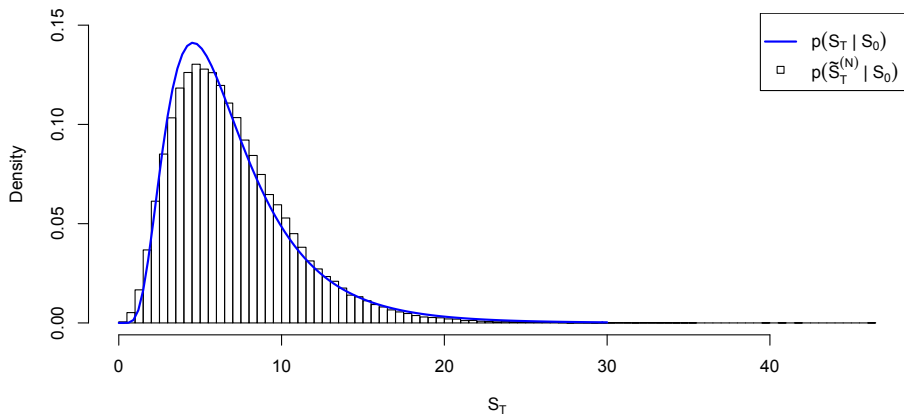
# Example: Geometric Brownian Motion

- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$
- ▶ **Simulation:**  $\alpha = .1, \sigma = .3, S_0 = 5.1, T = 3.2$  -  $N = 2$  ( $\Delta t = T/N$ )



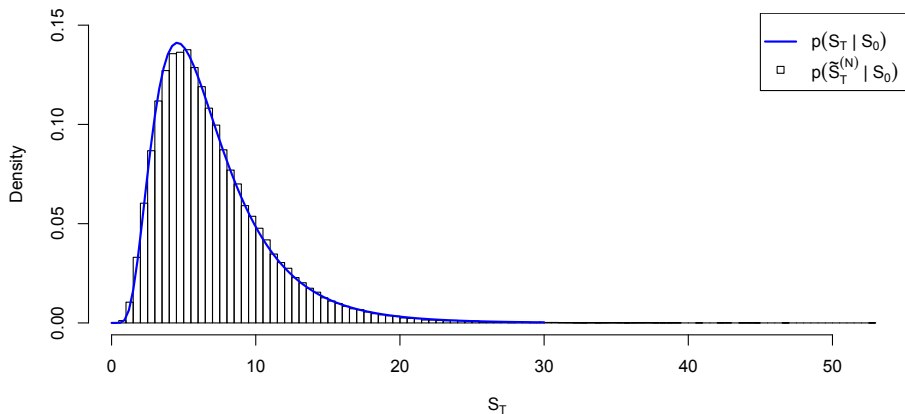
# Example: Geometric Brownian Motion

- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$
- ▶ **Simulation:**  $\alpha = .1, \sigma = .3, S_0 = 5.1, T = 3.2$  -  $N = 5$  ( $\Delta t = T/N$ )



# Example: Geometric Brownian Motion

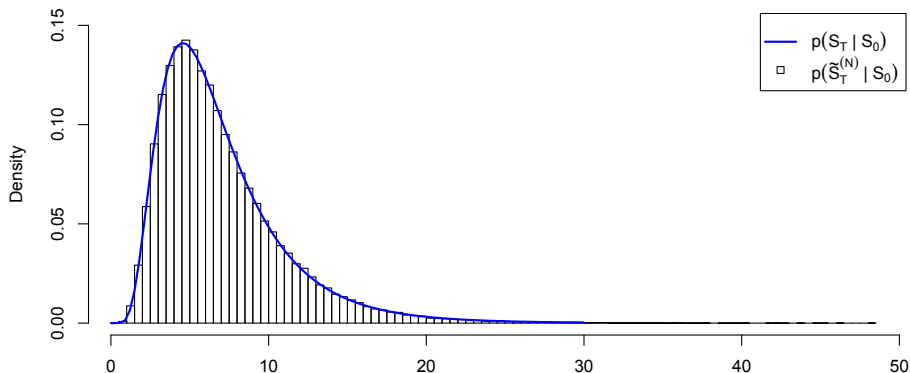
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$
- ▶ **Simulation:**  $\alpha = .1, \sigma = .3, S_0 = 5.1, T = 3.2$  -  $N = 20$  ( $\Delta t = T/N$ )





# Example: Geometric Brownian Motion

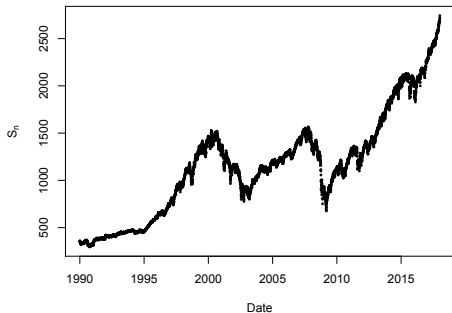
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$
- ▶ **Simulation:**  $\alpha = .1, \sigma = .3, S_0 = 5.1, T = 3.2$  -  $N = 100$  ( $\Delta t = T/N$ )



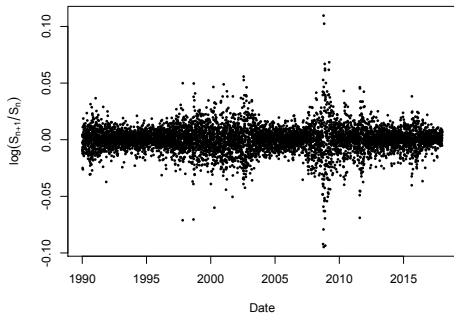
(In theory, don't know when  $N$  is large enough. In practice,  $N$  is large enough when increasing it doesn't change result.)

# Motivation (Continued)

GSPC: Original Scale ( $S_n$ )



GSPC: Log>Returns ( $\log(S_{n+1}/S_n)$ )



- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$
- ▶ **Model:** From 1900 till about 1989, this was a **stochastic differential equation** (SDE) called **Geometric Brownian motion**:

$$dS_t = \alpha S_t dt + \sigma S_t dB_t,$$

where  $S_t$  is the price at time  $t \in \mathbb{R}$  and  $B_t$  is Brownian motion.

# Motivation

- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$ .

Time between observations is  $\Delta t = 1/252$  years (as there are 252 trading days in one year).

- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$ .

- ▶ **Inference:** Let  $X_t = \log(S_t) = (\alpha - \frac{1}{2}\sigma^2)t + \sigma B_t$ . Then

$$\Delta X_i \stackrel{\text{iid}}{\sim} \mathcal{N}\left(\left(\alpha - \frac{1}{2}\sigma^2\right)\Delta t, \sigma^2 \Delta t\right).$$

- ▶ **MLE:**

- ▶ Let  $\mu = \left(\alpha - \frac{1}{2}\sigma^2\right)\Delta t$  and  $\tau^2 = \sigma^2 \Delta t$ .

- ▶ Thus  $\hat{\mu} = \frac{1}{N-1} \sum_{i=1}^{N-1} \Delta X_i$  and  $\hat{\tau}^2 = \frac{1}{N-1} \sum_{i=1}^{N-1} (\Delta X_i - \hat{\mu})^2$ .

(There are  $M = N - 1$  increments, and MLE of variance divides by sample size  $M$  – not  $M - 1$ , which is unbiased estimate)

# Motivation

- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$ ,  $\Delta t = 1/252$ .
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$ .
- ▶ **Inference:** Let  $X_t = \log(S_t)$ . Then  $\Delta X_i \stackrel{\text{iid}}{\sim} \mathcal{N}((\alpha - \frac{1}{2}\sigma^2)\Delta t, \sigma^2\Delta t)$ .
- ▶ **MLE:**
  - ▶ Let  $\mu = (\alpha - \frac{1}{2}\sigma^2)\Delta t$  and  $\tau^2 = \sigma^2\Delta t$ .
  - ▶ Thus  $\hat{\mu} = \frac{1}{N-1} \sum_{i=1}^{N-1} \Delta X_i$  and  $\hat{\tau}^2 = \frac{1}{N-1} \sum_{i=1}^{N-1} (\Delta X_i - \hat{\mu})^2$ .
  - ▶ **Invariance Property:** If the likelihood function is  $\ell(\boldsymbol{\theta} | \mathbf{X})$  and  $\boldsymbol{\eta} = g(\boldsymbol{\theta})$  is an invertible function, then

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} \ell(\boldsymbol{\theta} | \mathbf{X}) \quad \implies \quad \hat{\boldsymbol{\eta}} = g(\hat{\boldsymbol{\theta}}) = \arg \max_{\boldsymbol{\eta}} \ell(\boldsymbol{\eta} | \mathbf{X})$$

*Proof:* Whether you parametrize by  $\boldsymbol{\theta}$  or  $\boldsymbol{\eta}$ , the likelihood function takes on the same set of values, i.e.,  $\ell(\boldsymbol{\theta} | \mathbf{X}) = \ell(\boldsymbol{\eta} = g(\boldsymbol{\theta}) | \mathbf{X})$ . Therefore,

$$\ell(\boldsymbol{\eta} | \mathbf{X}) = \ell(\boldsymbol{\theta} = g^{-1}(\boldsymbol{\eta}) | \mathbf{X}) \leq \ell(\hat{\boldsymbol{\theta}} | \mathbf{X}) = \ell(\boldsymbol{\eta} = g(\hat{\boldsymbol{\theta}}) | \mathbf{X}).$$

# Motivation

- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$ ,  $\Delta t = 1/252$ .
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$ .
- ▶ **Inference:** Let  $X_t = \log(S_t)$ . Then  $\Delta X_i \stackrel{\text{iid}}{\sim} \mathcal{N}((\alpha - \frac{1}{2}\sigma^2)\Delta t, \sigma^2\Delta t)$ .
- ▶ **MLE:**
  - ▶ Let  $\mu = (\alpha - \frac{1}{2}\sigma^2)\Delta t$  and  $\tau^2 = \sigma^2\Delta t$ .
  - ▶ Thus  $\hat{\mu} = \frac{1}{N-1} \sum_{i=1}^{N-1} \Delta X_i$  and  $\hat{\tau}^2 = \frac{1}{N-1} \sum_{i=1}^{N-1} (\Delta X_i - \hat{\mu})^2$ .
  - ▶ **Invariance Property:**  $\hat{\sigma} = \sqrt{\hat{\tau}^2/\Delta t}$  and  $\hat{\alpha} = \hat{\mu}/\Delta t + \frac{1}{2}\hat{\sigma}^2$ .

# Motivation

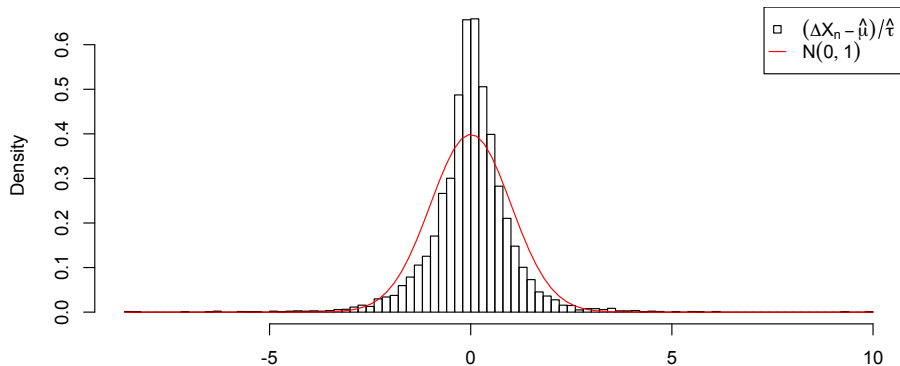
- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$ ,  $\Delta t = 1/252$ .
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$ .
- ▶ **Inference:** Let  $X_t = \log(S_t)$ . Then  $\Delta X_i \stackrel{\text{iid}}{\sim} \mathcal{N}((\alpha - \frac{1}{2}\sigma^2)\Delta t, \sigma^2\Delta t)$ .
- ▶ **MLE:**
  - ▶ Let  $\mu = (\alpha - \frac{1}{2}\sigma^2)\Delta t$  and  $\tau^2 = \sigma^2\Delta t$ .
  - ▶ Thus  $\hat{\mu} = \frac{1}{N-1} \sum_{i=1}^{N-1} \Delta X_i$  and  $\hat{\tau}^2 = \frac{1}{N-1} \sum_{i=1}^{N-1} (\Delta X_i - \hat{\mu})^2$ .
  - ▶ *Invariance Property:*  $\hat{\sigma} = \sqrt{\hat{\tau}^2/\Delta t}$  and  $\hat{\alpha} = \hat{\mu}/\Delta t + \frac{1}{2}\hat{\sigma}^2$ .
- ▶ **Goodness-of-Fit:** If model is correct, then approximately we have

$$Z_i = (\Delta X_i - \hat{\mu})/\hat{\tau} \stackrel{\text{iid}}{\sim} \mathcal{N}(0, 1).$$

# Motivation

- ▶ **Data:** Daily GSPC closing prices  $\mathbf{S} = (S_1, \dots, S_N)$ ,  $\Delta t = 1/252$ .
- ▶ **Model:**  $dS_t = \alpha S_t dt + \sigma S_t dB_t$ . Let  $X_t = \log(S_t)$ . Then  $\Delta X_i \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \tau^2)$ .
- ▶ **Goodness-of-Fit:** If model is correct, then approximately we have

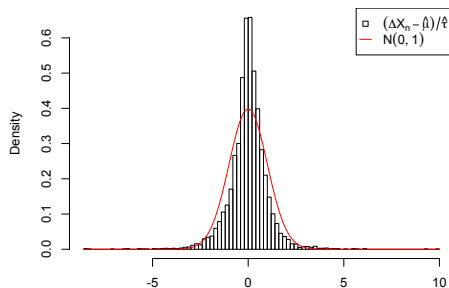
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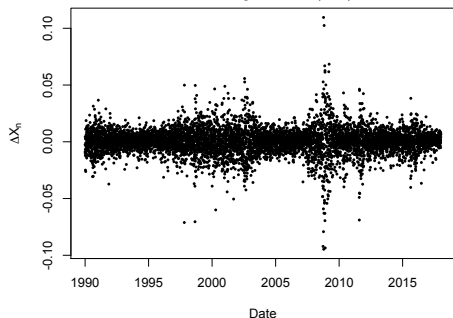
# Motivation

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Goodness-of-Fit



GSPC: Log>Returns ( $\Delta X_n$ )



Assumption of **constant volatility** ( $\sigma$ ) is violated.



# Stochastic Volatility Modeling

- ▶  $S_t$ : value of GSPC at time  $t$ .
- ▶ **Constant-Volatility Model:** Let  $X_t = \log(S_t)$ . Then gBM model on log scale is

$$dX_t = \left(\alpha - \frac{1}{2}\sigma^2\right) dt + \sigma dB_t.$$

- ▶ **Stochastic Volatility Model:**

- ▶ *Idea:* Replace  $\sigma^2$  by time-dependent volatility  $V_t$ :  $dX_t = \left(\alpha - \frac{1}{2}V_t\right) dt + V_t^{1/2} dB_t$
- ▶ *Problem:*  $V_t$  is an infinite-dimensional parameter, so need to *regularize* to estimate it.
- ▶ *Solution:* Give another SDE to  $V_t$ . Thus we get the two-dimensional process

$$\begin{aligned}dX_t &= \left(\alpha - \frac{1}{2}V_t\right) dt + V_t^{1/2} dB_{1t}, \\dV_t &= -\gamma(V_t - \mu) dt + \sigma V_t^\lambda dB_{2t}.\end{aligned}$$

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- ▶ **Stochastic Volatility Model:**
  - ▶ *Idea:* Replace  $\sigma^2$  by time-dependent volatility  $V_t$ , and give another SDE to  $V_t$ . Thus we get the two-dimensional process

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$$dV_t = -\gamma(V_t - \mu) dt + \sigma V_t^\lambda dB_{2t}.$$

- ▶ *Parameter Interpretation:*
  - ▶  $\alpha$ : “interest” rate:  
 $E[S_t] = S_0 e^{\alpha t}$
  - ▶  $\mu = E[V_t]$ : long-run mean
  - ▶  $\gamma$ : mean-reversion:  
 $\text{cor}(V_s, V_{s+t}) = e^{-\gamma t}$
  - ▶  $\sigma$  and  $\lambda$ : scale and shape

# Stochastic Volatility Modeling

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► Euler Approximation:

$$\begin{bmatrix} \Delta X_t \\ \Delta V_t \end{bmatrix} \sim \mathcal{N} \left\{ \begin{bmatrix} \alpha - \frac{1}{2}V_t \\ -\gamma(V_t - \mu) \end{bmatrix} \Delta t, \begin{bmatrix} V_t & 0 \\ 0 & \sigma^2 V_t^{2\lambda} \end{bmatrix} \Delta t \right\}$$

# Parameter Inference

► **Data:** Daily GSPC log-prices  $\mathbf{X} = (X_1, \dots, X_N)$ ,  $\Delta t = 1/252$ .

► **Stochastic Volatility Model:**

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► **Likelihood:**  $\ell(\boldsymbol{\theta} | \mathbf{X}) = ???$  Two **complications**:

1.  $\mathcal{L}(\boldsymbol{\theta} | \mathbf{X}, \mathbf{V}) \propto p(\mathbf{X}, \mathbf{V} | \boldsymbol{\theta}) = \prod_{n=1}^{N-1} p(X_{n+1}, V_{n+1} | X_n, V_n, \boldsymbol{\theta})$ .

However, the *transition density*  $p(X_{n+1}, V_{n+1} | X_n, V_n, \boldsymbol{\theta})$  is not available in closed form (solution to a PDE).

2.  $\mathcal{L}(\boldsymbol{\theta} | \mathbf{X}) \propto p(\mathbf{X} | \boldsymbol{\theta}) = \int p(\mathbf{X}, \mathbf{V} | \boldsymbol{\theta}) d\mathbf{V}$ .

That is, the volatility process is *latent* (completely unobserved), and hence must be integrated out.

# Parameter Inference

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However,  $p(X_{n+1}, V_{n+1} | X_n, V_n, \boldsymbol{\theta})$  is intractable.

**Solution:** Use Euler approximation!

$$\begin{bmatrix} \Delta X_{n+1} \\ \Delta V_{n+1} \end{bmatrix} \sim \mathcal{N} \left\{ \begin{bmatrix} \alpha - \frac{1}{2}V_n \\ -\gamma(V_n - \mu) \end{bmatrix} \Delta t, \begin{bmatrix} V_n & 0 \\ 0 & \sigma^2 V_n^{2\lambda} \end{bmatrix} \Delta t \right\}$$

(Results are approximate, but reportedly good enough for daily financial data)

# Parameter Inference

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That is, the latent volatility process must be integrated out.

**Solution:** Replace  $V_t$  by an observable market proxy.

# Parameter Inference

## ► Data:

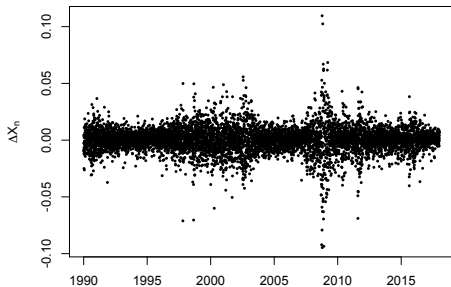
- $X_i$ : log GSPC value on day  $i$
- $V_i$ : VIX value on day  $i$  (measure of implied volatility determined by CBOE)

## ► Stochastic Volatility Model:

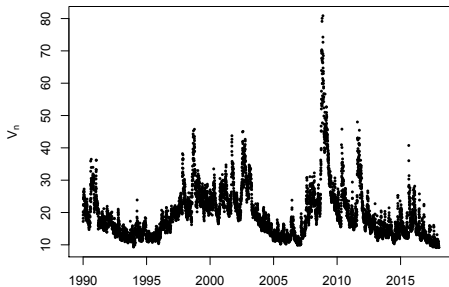
( $\tau$  is the VIX scale adjustment)

$$\begin{aligned}dX_t &= \left(\alpha - \frac{1}{2}\tau V_t\right) dt + (\tau V_t)^{1/2} dB_{1t}, \\dV_t &= -\gamma(V_t - \mu) dt + \sigma V_t^\lambda dB_{2t}.\end{aligned}$$

GSPC: Log>Returns ( $\Delta X_n$ )



VIX ( $V_n$ )



# Parameter Inference

► **Data:**  $\mathbf{Y}_i = (X_i, V_i)$ : (log-GSPC, VIX) pair on day  $i$ .  $\mathbf{Y} = (\mathbf{Y}_1, \dots, \mathbf{Y}_N)$ .

► **Stochastic Volatility Model:**

$$dX_t = (\alpha - \frac{1}{2}\tau V_t) dt + (\tau V_t)^{1/2} dB_{1t}$$

$$dV_t = -\gamma(V_t - \mu) dt + \sigma V_t^\lambda dB_{2t},$$

► **Loglikelihood:** For  $\theta = (\alpha, \gamma, \mu, \sigma, \lambda, \tau)$ , [Euler approximation](#) gives

$$\begin{aligned} \ell(\theta | \mathbf{Y}) &= \sum_{i=1}^{N-1} \log p(\mathbf{Y}_{i+1} | \mathbf{Y}_i, \theta) \\ &\approx -\frac{1}{2} \sum_{i=1}^{N-1} \left\{ \frac{[\Delta X_i - (\alpha - \frac{1}{2}\tau V_i)\Delta t]^2}{\tau V_i \Delta t} + \log(\tau V_i \Delta t) \right\} \\ &\quad - \frac{1}{2} \sum_{i=1}^{N-1} \left\{ \frac{[\Delta V_i + \gamma(V_i - \mu)\Delta t]^2}{\sigma^2 V_i^{2\lambda} \Delta t} + \log(\sigma^2 V_i^{2\lambda} \Delta t) \right\} \end{aligned}$$

(each term is the log-pdf of a univariate normal)



# Parameter Inference

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► **Loglikelihood:** Let  $\theta = (\alpha, \gamma, \mu, \sigma, \lambda, \tau)$ .

► Euler approximation:

$$\ell(\theta | \mathbf{Y}) \approx \sum_{i=1}^{N-1} \log \varphi_X(\Delta X_i | \mathbf{Y}_i, \theta) + \log \varphi_V(\Delta V_i | \mathbf{Y}_i, \theta),$$

where  $\varphi_X(\cdot | \mathbf{Y}, \theta)$  and  $\varphi_V(\cdot | \mathbf{Y}, \theta)$  are univariate normal PDFs specified by SV model.

► **MLE:**  $\hat{\theta} = \arg \max_{\theta} \ell(\theta | \mathbf{Y})$  does not have an analytic solution, so use R function `optim` for numerical optimization. (See `?optim` for details!)

# Parameter Inference

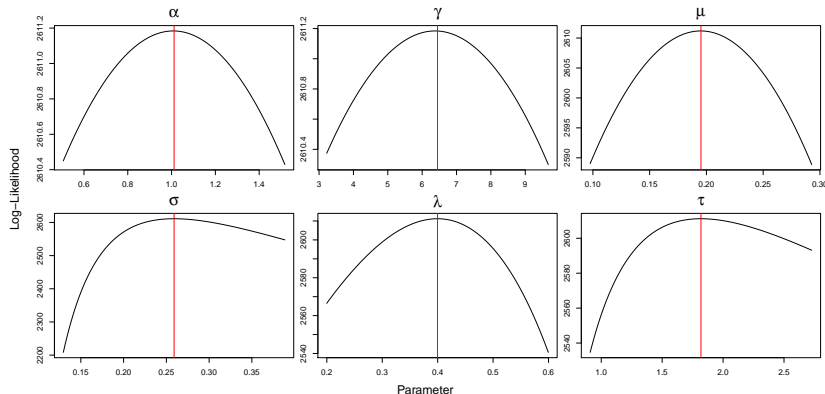
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► **Simulation:**

Parameter	$\alpha$	$\gamma$	$\mu$	$\sigma$	$\lambda$	$\tau$	$X_0$	$V_0$	$N$	$\Delta t$
Value	.1	.5	.2	.3	.5	2	6.5	.2	500	1/252



Good algorithm initialization:  $\theta_{\text{init}} = \theta_{\text{true}}$ .

# Parameter Inference

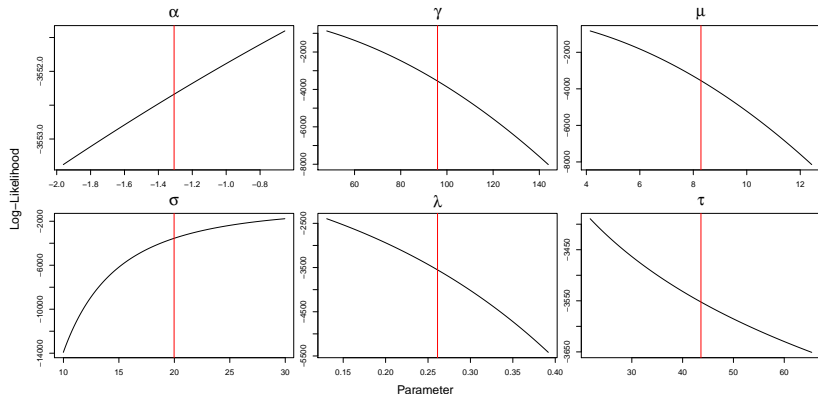
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Bad algorithm initialization:  $\theta_{\text{init}} = 10 \times \theta_{\text{true}}$ .

# Resources

- ▶ [msde](#): An R/C++ package for simulation/inference with multivariate SDEs having latent variables (e.g., SV model with  $V_t$  not proxied by VIX).